

# METHOD FOR FINDING QUOTIENT IN A DIGITAL SYSTEM

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### BACKGROUND OF THE INVENTION

The present invention relates to a method for finding a quotient, especially to a method for finding a quotient in a digital system by signed-digit operation.

Inherently, division operation is sequential operation. The quotient digits are produced only after the sign of the remainder have been detected. As a result, division operation is much slower than multiplication operation. Efforts have been put in speeding up the division It is noted that the SRT algorithm (C. V. Freiman, "Statistical Analysis of Certain Binary division algorithms," Proc. IRE, Vol. 49, Jan. 1961, pp. 91-103; K. Hwang, Computer Arithmetic: Principles, Architectures, and 1979, pp. Design. 222-223) eliminates the restoring operations of the partial remainders. Another algorithm disclosed by K. Hwang in the aforementioned article confines the quotient digits either to be 1 or -1, depending on the signs of remainders. However, the bottleneck of those

algorithms lies in sign detection of the remainder. Fast addition algorithms such as CLA (carry-lookahead addition) shorten the operation time, but results in complex hardware structures. The aforementioned articles of C. V. Freiman and K. Hwang are hereby incorporated herein by reference.

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Recently, division algorithms based on SD (signeddigit) number representation was proposed which is much faster than the previous algorithm (S. Kuninobu et al., "Design of High Speed MOS Multiplier and Divider Using Representation," Redundant Binary IEEE Proceeding Symposium on Computer Arithmetic, 1987, pp. 80-86). This algorithm considerably shortens the time for remainder subtraction by using carry-propagation-free SD addition. However, it is much more complex because in each iteration the SD algorithm must check three most significant digit (MSD) bits of the remainder to decide the quotient digit in the set of  $\{-1, 0, 1\}$ , and then perform the SD addition. Moreover, the final SD result must be converted to binary representation. Also note that the signed-digit addition is more complicated than the conventional carry-save adder (CSA).

Another type of algorithms entirely avoids the slow subtract-detect-shift type of operation previously

mentioned. They transform the division operation to a series of multiplication operations that converge to the original quotient. Among the examples are the constant convergence (S. Waser and M. J. Flynn, Introduction to Arithmetic for Digital Systems Designers, New York: CBS College Publishing, Chap. 5, 1982) and quadratic convergence (P. Markenstein, of Elementary Functions the IBM RISC "Computation on System/6000 Processor," IBMJournal of Research and Development, Vol. 34, 1990, pp. 111-119; D. A. Patterson and Hennessy, Computer: A Quantitative Approach, Mateo, CA, Morgan Kaufman, 1990) division algorithms which are based on Newton-Raphson algorithm. They are often found in multiplier-based processors. They are still sequential type of operation to certain degree, and obviously require much more shift-and-add operations.

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There is an on-line division algorithm that facilitates serial/serial division operation (K. S. Trivedi and M. D. Ercegovac, "On-Line Algorithms for Division and Multiplication," IEEE Trans. on Computers, Vol. C-26, No. 7, July 1977). This algorithm has advantages such as that: (a) it is pipelined at digit level; (b) all operands and results are communicated digit serial, and (c) result digits are online obtained after a few initial delay. On the other hand, among some of its disadvantages are: (a) it requires more

complex three-input signed-digit addition operation; (b) it needs more complicated quotient decision circuit for range detection of the remainder, and (c) output results have to be converted to binary representations.

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### SUMMARY OF THE INVENTION

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In this work, a fast radix-2 division algorithm and its architecture is proposed. The algorithm adheres shift/subtract-and-add type of division operation. The key idea behind this algorithm is to separate the sign detection operation of remainder from the remainder subtraction operation. By taking the absolute values of the remainders, we can successively subtract the remainders without the need of knowing the signs of remainders, while signs of the remainders can be decided in parallel and independently at To enhance the algorithm's performance, the same time. techniques incorporated its design were into architecture realization.

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The new algorithm and its architecture try to retains the most advantages of the mentioned algorithms as possible, and simultaneously gets rid of their disadvantages. The

algorithm adopts non-restoring division operation and CSA type of operation for fast subtraction. Quotient digit set of {1, -1} is assumed for fast quotient conversion to binary representation. The algorithm is also an on-line algorithm that facilitates highly pipelined operation while it is much simpler than the existing on-line algorithms.

This object of the present invention are fulfilled by providing a method for finding a quotient  $Q = a_0 a_1 a_2 \dots a_b$ from a divisor  $Y = y_1 y_2 \dots y_n$  and a dividend  $X = x_1 x_2 \dots x_n$ . The method comprises the following steps of: (a) aligning the first non-zero bit of X with the first non-zero digit of Y; (b) defining a signed-digit partial remainder series R where  $R_n = Y$ , a first sign series of the partial remainder  $S_i$ where  $S_0 = 0$ , a second sign series of the partial remainder  $S_n$ , and a counter i beginning from zero; (c) subtracting X from R which yields next signed-digit partial remainder  $R_{i+1}$ ; (d) setting the sign of  $R_{i+1}$  to  $S_{r_{i+1}}$ ; (e) setting the result of exclusive-OR of  $S_i$  and  $S_{p_{i+1}}$  to the true sign of the next remainder  $S_{i+1}$ ; (f) setting  $a_i$  to 1 if  $S_{i+1} = 0$  or  $R_{i+1} = 0$ ; (g) setting  $a_i$  to 0 if  $S_{i+1} = 1$ ; (h) inverting the signs of all digits of  $R_{i+1}$  if  $S_{i+1} = 1$ ; (i) shift  $R_{i+1}$  left by one bit; (j) adding 1 to i; and (k) repeating said steps (c) to (j) until i reaches a predetermined value or  $R_{i+1} = 0$ .

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Further scope of applicability of the present invention will become apparent from the detailed description given hereinafter. However, it should be understood that the detailed description and specific examples, while indicating preferred embodiments of the invention, are given by way of illustration only, since various changes and modifications within the spirit and scope of the invention will become apparent to those skilled in the art from this detailed description.

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### DETAILED DESCRIPTION OF THE EMBODIMENTS

15 For achieving fast division, a new division algorithm is proposed and discussed hereinafter.

### NEW DIVISION ALGORITHM

Given normalized n-bit sign magnitude operands  $1/2 \le |X| < 1$ ,  $1/2 \le |Y| < 1$  (this limitation is used to automatically align the first non-zero bit of X with the first non-zero digit of Y in the later discussion, which is avoided in circuit realization), quotient  $Q_2$  of Y/X can be solved using the following principles, where the quotient digits

 $Q_2=a_1a_0\cdot a_1a_2\dots a_n$  is in sign-magnitude representation and  $a_i$  is the sign bit.

# Principle 1:

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a, equals to the result of exclusive-OR of the sign bits  $y_i$  and  $x_i$  of Y and X, respectively, i. e.,  $a_i = y_i \oplus x_i$ .

# Principle 2:

Partial remainder  $R_{i+1}$  can be solved by modifying the conventional, nonrestoring algorithm stated by K. Hwang as follows. The signed-binary quotient Q has its quotient digit  $q_i \in \{1, -1\}$ , and

$$R_{i,i} = 2 | R_i - q_{i,i} ' X | \qquad ----- (1)$$

where  $R_0 = |Y|$ ,  $q_0 = 1$ ,  $q_i'$  is the i-th pseudo quotient digit. Since  $R_{i+1}$  is always positive, Eq. (1) can be rewritten as

$$R_{i+1} = 2 |R_i - X| \qquad ------ (2)$$

$$q_{i+1} = \begin{cases} 1, & \text{if } S_{i+1} = 0 \\ 1, & \text{if } Z_{i+1} = 1 \\ -1, & \text{if } S_{i+1} = 1 \end{cases} \qquad ----- (3)$$

$$a_i = \begin{cases} 1, & \text{if } q_{i+1} = 1 \\ 0, & \text{if } q_{i+1} = -1 \end{cases} \qquad ----- (4)$$

25 where

 $\mathbf{S}_{r_i}$  = The sign of remainder ( $\mathbf{R}_{_i}$  - X),  $\mathbf{S}_{_i}$  = True sign of i-th remainder =  $\mathbf{S}_{_{i:1}} \oplus \mathbf{S}_{r_i}$  ,

$$Z_i = Zero Flag, Z_0 = 0$$
, and  $S_0 = S_{ro} = Sign(R_0) = 0$ .

The algorithm can be performed using the method described below.

#### **NEW DIVISION METHOD**

Define signed magnitude numbers  $Y_s = y_s \cdot y_1 y_2 \cdot \cdot \cdot \cdot y_n$ ,  $X_s = x_s \cdot x_1 x_2 \cdot \cdot \cdot x_s$ , and  $Q_s = q_1 q_0 \cdot q_1 q_2 \cdot \cdot \cdot \cdot q_s$  in signed-binary representation,  $q_s \in \{-1, 1\}$ , and converted to sign magnitude representation  $Q_2 = a_s a_0 \cdot a_1 a_2 \cdot \cdot \cdot \cdot a_s$ ,  $a_s \in \{0, 1\}$ . The quotient  $Q_s$  of  $X_s / Y_s$  can be solved by the following steps:

15 Step 1:

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$$a_i = y_i \oplus x_i$$
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Step 2:

Define 
$$Y = y_1 y_2 \dots y_n$$
,  $X = x_1 x_2 \dots x_n$ ,  $Q = a_0 a_1 a_2 \dots a_b$ ,  
20  $R_0 = Y$ ,  $i = 0$ , and  $S_0 = 0$ .

Step 3:

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Subtract X from  $R_i$  and yield next signed-digit partial remainder  $R_{i+1}$ . Set the sign of  $R_{i+1}$  to  $S_{r_{i+1}}$  (note that the sign of  $R_{i+1}$  equals the sign of first non-zero digit of  $R_{i+1}$ ).

Set the result of  $S_i \oplus S_{r_{i+1}}$  to the true sign of the next remainder  $S_{i+1}$ . Set  $a_i$  to 1 if  $S_{i+1} = 0$  (means the remainder is positive) or  $R_{i+1} = 0$ . Set  $a_i$  to 0 if  $S_{i+1} = 1$  (means the remainder is negative).

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### Step 4:

If  $S_{i+1}=1$ , then take the absolute value of  $R_{i+1}$  (by inverting the signs of all digits). Shift  $R_{i+1}$  left by one bit. Add 1 to i. Repeat step 3 until i reaches a predetermined value or  $R_{i+1}=0$ .

For better comprehension, two examples are used to demonstrate the division method hereinafter:

## EXAMPLE 1:

$$Y = 01010001_2 = 81$$

 $X = 00001001_2 = 9$  (X will be shifted left 3 places to align its highest non-zero digit with highest non-zero digit of  $R_0$ )

— <b>,</b>	1010001	$R_0 = Y$
	-1001000	x
10		
1216	0001001	$R_1 > 0$ then $S_{r_1} = 0$ ,
1-11		$S_1 = S_{r_1} \oplus S_0 = 0, a_0 = 1$
11)	SHIFT LEFT ONE BIT	1 /1 0
. [	0010010	•
15	- 1001000	X
	·	
	-0110110	$R_{2} < 0$ then $S_{r_{2}} = 1$ ,
	• •	$S_2 = S_{r_2} \oplus S_1 = 1, a_1 = 0$
	TAKE ABSOLUTE VALUE	2 72 1
20	0110110	
	SHIFT LEFT ONE BIT	
	1101100	
	- 1001000	X
25	0100100	$R_3 > 0 \text{ then } S_{r_3} = 0,$
		$S_3 = S_{r_3} \oplus S_2 = 1, a_2 = 0$
	SHIFT LEFT ONE BIT	•
	1001000	
	- 1001000	X
30		D - 0 Abam 1
	0000000	$R_4 = 0$ then $a_3 = 1$

Result:

The quotient =  $a_0 a_1 a_2 a_3 = 1001_2 = 9$ , and remainder = 0



In this example, note that a digit with a bar means a digit having negative value, e. g.

$$Y = 10101110_{2} = 174$$

$$X = 11_{2} = 3$$

10101110

01101110 SHIFT LEFT ONE BIT

$$\overline{100\overline{111}00} \quad R_{2} < 0 \text{ then } S_{r_{2}} = 1,$$

$$S_{2} = S_{r_{2}} \oplus S_{1} = 0, a_{1} = 1$$
Take absolute value

X

 $\mathbf{X}$ 

X

X

20. TAKE ABSOLUTE VALUE

10011100 SHIFT LEFT ONE BIT

01111000 
$$R_3 > 0$$
 then  $S_{r_3} = 0$ ,  $S_3 = S_{r_3} \oplus S_2 = 0$ ,  $A_2 = 1$ 

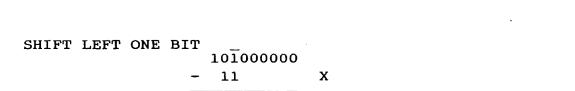
00110000 
$$R_4 > 0 \text{ then } S_{r_4} = 0, S_4 = S_{r_4} \oplus S_3 = 0, a_3 = 1$$

SHIFT LEFT ONE BIT 35

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To 1000000 R < 0 then 
$$S_{r_5} = 1$$
,  $S_5 = S_{r_5} \oplus S_4 = 1$ ,  $S_4 = 0$ 

The value  $S_{r_5} = S_{r_5} \oplus S_4 = 1$ ,  $S_{r_5} = 1$ ,  $S_{r_5}$ 



The quotient =  $a_0 a_1 a_2 a_3 a_4 a_5 a_6 = 0111010_2 = 58$ , and remainder = 0

00000000  $R_6 = 0$  then  $a_5 = 1$ ,  $a_6 = 0$ 

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Since absolute values of the partial remainders are computed instead of their actual values, the algorithm facilitates parallel computations of partial remainder and quotient digit. To further speed up the operation of subtraction in the preferred embodiment, we use specified signed-digit operation.

### SPECIFIED SIGNED-DIGIT SUBTRACTION

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Since computations of Eq. (2) involves only the subtraction operation of two positive numbers,  $R_i$  and X, we can speed up the computation by defining the CSA-like operation as follows.

$$y_{j} - x_{j} = 2c_{j+1} + t_{j}$$
 ----- (5.a)  
 $t_{j} + c_{j} = r_{j}$  ----- (5.b)  
wherein  $y_{i}$ ,  $r_{i} \in \{-1, 0, 1\}$ 

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$$x_{j}, t_{j} \in \{0, 1\}$$
 $c_{i} \in \{-1, 0\}.$ 

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Here, a signed-digit  $y_j$  (represents the j-th digit of  $R_i$ ) subtracts a binary digit  $x_j$ , then generates carry  $c_{j+1}$  and intermediate result  $t_j$ . The finial result  $r_j$  (represents the j-th digit of  $R_{i+1}$ ) is obtained by adding  $t_j$  and the carry-in bit  $c_j$ . Since  $r_j \in \{-1, 0, 1\}$ , there will be no carry generated from  $t_j + c_j$ . As a result, the specified signed-digit subtraction efficiently eliminates carry propagation. In addition, the complexity of this operation is similar to that of conventional CSA. Example 3 depicts the modified subtraction method where  $T_i = t_1 t_2 \dots t_n$  and  $c_i = c_1 c_2 \dots c_n$ .



$$Y = 01010001_2 = 81$$

$$X = 00001001_2 = 9$$

5	1010001	$R_0 = Y$
	-1001000	x
2	0011001	T,
	-0001000	C,
10	0001001	$R_{1} > 0$ then $S_{r_{1}} = 0$ ,
	SHIFT LEFT ONE BIT	$S_1 = S_{r_1} \oplus S_0 = 0, a_0 = 1$
-	0010010	·
15	- 1001000	х
~	1011010	$\mathbf{T_2}$
	-1001000	$C_2^2$
20	11001010	$R_2 < 0$ then $S_{r_2} = 1$ ,
20		$S_{2} = S_{p_{2}} \oplus S_{1} = 1, a_{1} = 0$
	TAKE ABSOLUTE VALUE 11001010	
	SHIFT LEFT ONE BIT	
25	110010100	
	- 1001000	X
	111011100	T <sub>3</sub> .
30	-011011100	C <sub>3</sub>
30	$001\overline{1}00100$	$R_3 > 0$ then $S_{r_3} = 0$ ,
		$S_3 = S_{r_3} \oplus S_2 = 1$ , $A_2 = 0$
	SHIFT LEFT ONE BIT	•
35	- 1001000	X
	10000000	T C <sub>4</sub>
	-01000000	C <sub>4</sub>
40		$R_4 = 0$ then $a_3 = 1$

Result:

The quotient =  $1001_2$  = 9, and remainder = 0

As shown in the above example,  $T_i$  and  $C_i$  are calculated first, then  $R_i$  can be easily decided. The truth table of  $t_j$  and  $c_{j+1}$  value are listed in table 1, where the signed-digit  $r_j$  of  $R_i$  is represented by two bits,  $r_j^1$  and  $r_j^2$ .  $r_j^1 = \text{sign}\{r_j\}$ .  $r_j^2 = |r_j|$ .

10 TABLE 1:

TRUTH TABLE OF  $t_i$  AND  $c_{i+1}$ 

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$\mathbf{r}_{j}^{1}$	$\mathbf{r}_{_{\mathbf{j}}}^{^{2}}$	<b>C</b> <sub>j+1</sub>	t,
0	0	0	0
0	1	0	1
1	1	1	1
0	0	1	1
0	1	0	0
1	1	1	0
	0 0 1 0	0 0 0 1 1 1 0 0 0 0 1	0     0       0     1       0     1       1     1       0     0       1     0

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Note that  $r_i$  represents j-th digit of  $R_i$  here.

The truth table of  $r_j$  (represents the j-th digit of  $R_{i+1}$ ) is listed in table 2.

TABLE 2:

TRUTH TABLE OF  $r_i$  (the j-th digit of  $R_{i+1}$ )

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C <sub>j</sub>	t,	$\mathbf{r}_{j}^{1}$	$\mathbf{r}_{j}^{2}$
0	0	0	0
0	1	0	1
1	0	1	1
1	1	0	0

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From the above tables we can see that the signed-digit subtraction can be achieved by a simple digital circuit, and can be pipe-lined for better performance.

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### CONCLUSION

In summary, the division algorithm have the advantages as follows:

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a) It uses a smaller quotient digit set of {1, -1} than {-1, 0, 1}, that simplifies that quotient decision circuits like some known algorithms do, but achieves the exact division and trivial conversion of the results from signed-binary representation to binary representation.

- b) It needs no quotient estimator.
- c) In each iteration, the algorithm computes partial remainders without knowing the signs of previous remainders and decides the signs of remainders independently and in parallel. In addition, these two operations are done in pipelined fashion and in digit level with maximum throughput rate.

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- d) Its architecture <del>is</del> basically consists of the simple CSA type cells.
  - e) It can handle either positive or negative operands.

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From above discussion, the proposed division algorithm and its architecture is very efficient. The new algorithm's realization is composed of highly regular cellular array, which is suitable for VLSI implementation and can be easily extended to bit-parallel implementation.

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The algorithm can be extended to higher radix divisions such as radix-4 division. Since the remainders are taken absolute values, the digit set contains only digits 1 and 2 is sufficient for the entire radix-4 operation. This greatly



reduces the number of search regions for the quotient digits, in contrast to the bigger set of  $\{0, 1, 2, 3\}$  that existing algorithms allow.

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While the invention has been described by way of an example and in terms of several preferred embodiments, it is to be understood that the invention need not be limited to the disclosed embodiment. On the contrary, it is intended to various modifications and similar arrangements cover included within the spirit and scope of the appended claims, accorded the scope of which should be the interpretation so as to encompass all such modifications and similar structures.